

Static Termination Analysis for Event-driven Distributed Algorithms

Felix Wiemuth^{1 2}

Peter Amthor¹

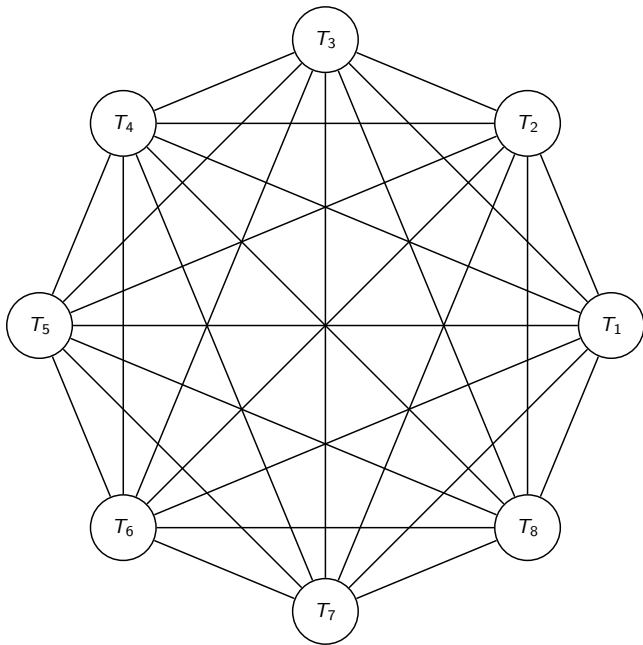
Winfried E. Kühnhauser¹

¹Technische Universität Ilmenau
Ilmenau, Germany

²**Concordium Research ApS**
Aarhus, Denmark

June 28, 2019

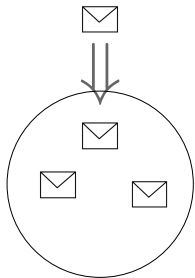
- **Termination**
 - Important non-functional property
 - Undecidable
- **Approach**
 - Event-based model
 - Criterion implying termination



message-based
point-to-point
asynchronous

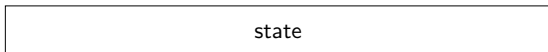
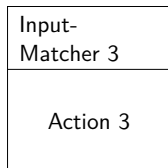
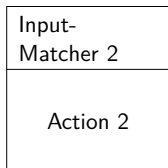
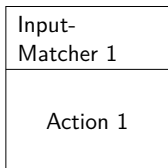
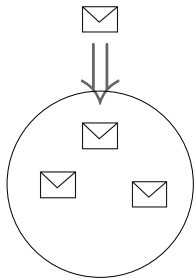


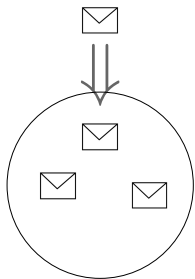
state



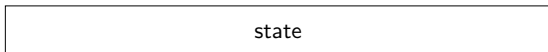
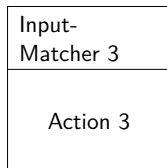
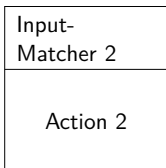
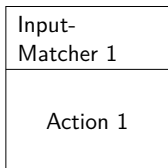
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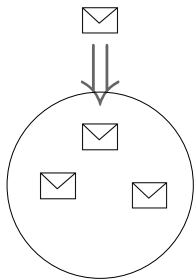
Model: Tasks



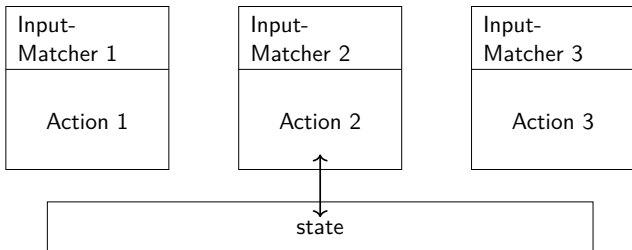


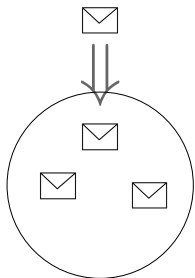
Guarded commands
(Dijkstra 1975)



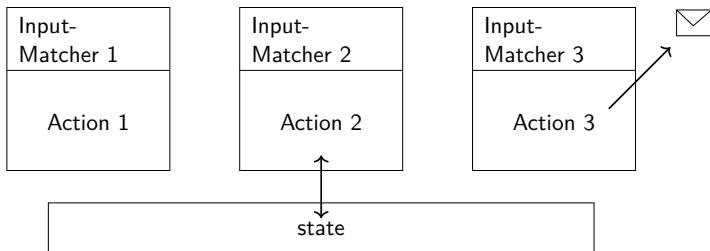


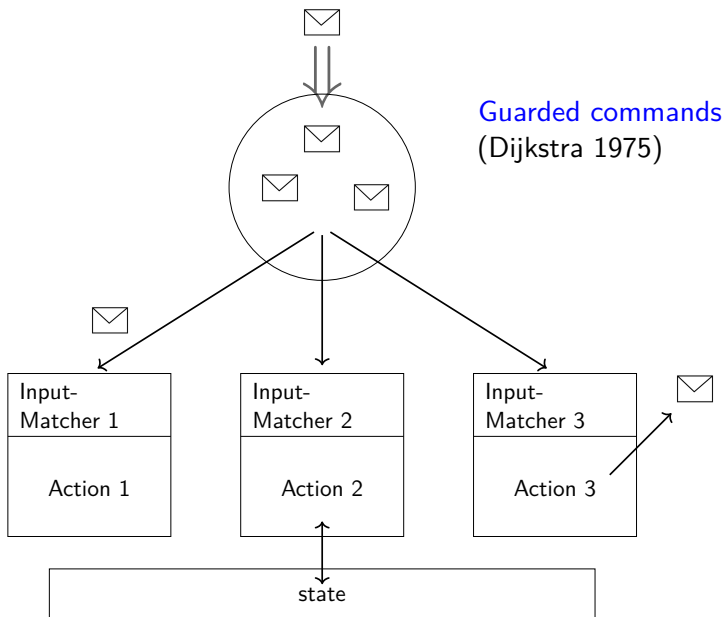
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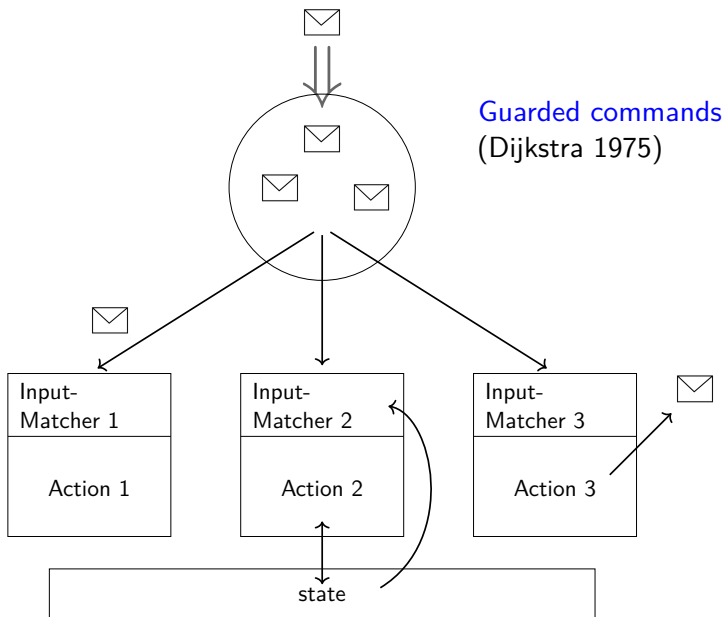


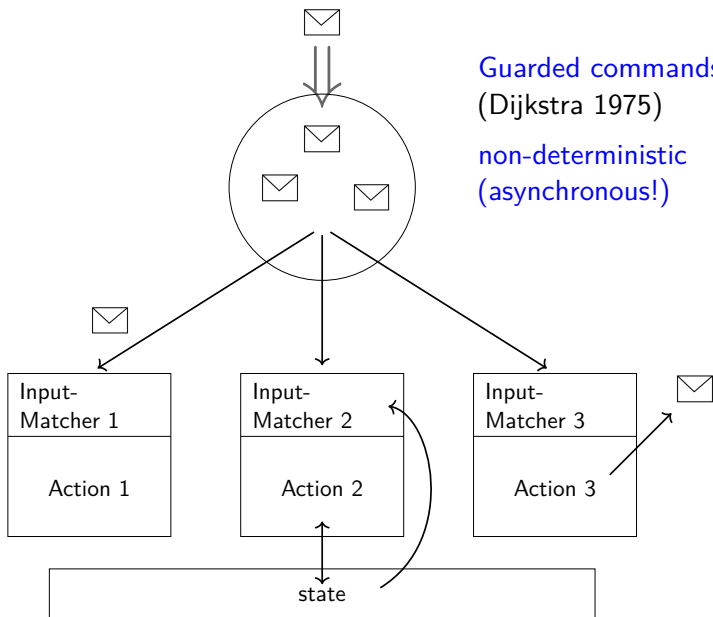


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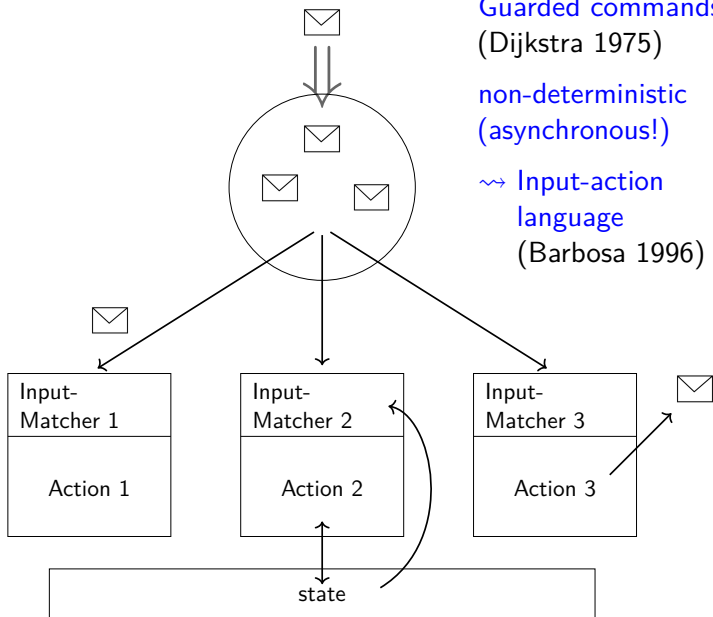






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non-deterministic
(asynchronous!)

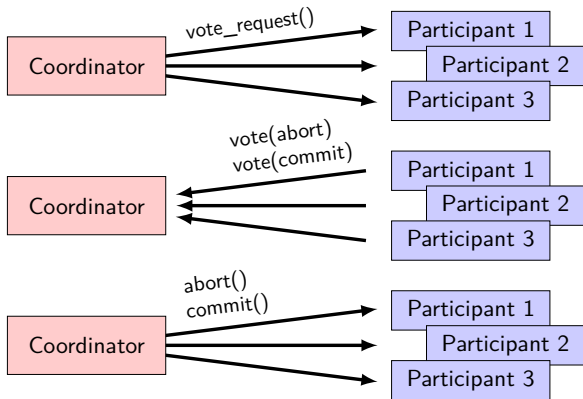


Guarded commands
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non-deterministic
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↪ Input-action
language
(Barbosa 1996)

Two-phase commit protocol



Two-phase commit protocol

Participant: $P = \{P_1, \dots, P_n\}$

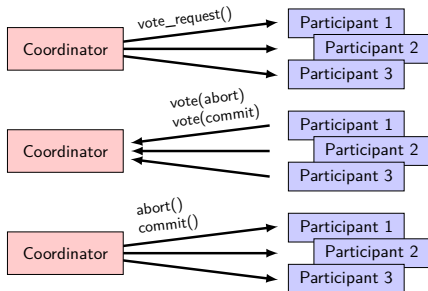
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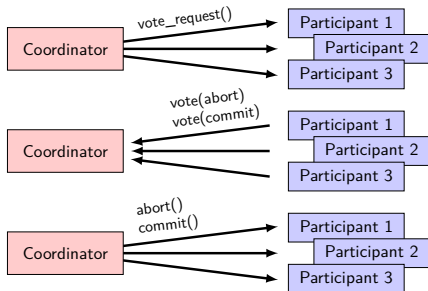
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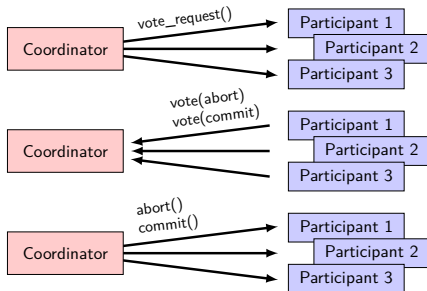
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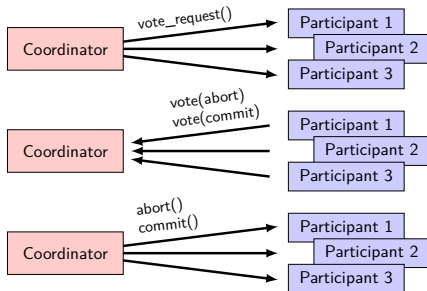
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P.abort()

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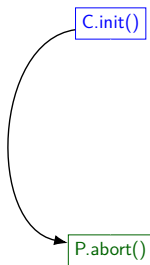
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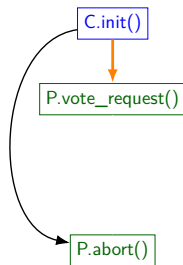
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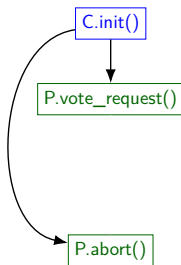
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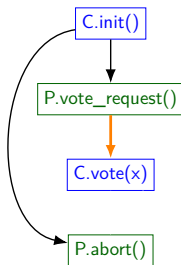
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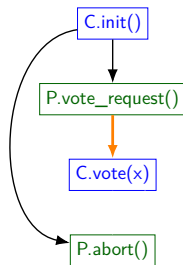
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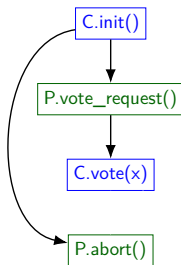
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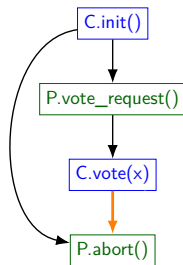
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  t.commit()  
}
```



Message flow in the two-phase commit protocol

Coordinator: { C }

Variables

t // local part of transaction
v // own vote (commit/abort)
count := 0 // commit count

```
input init() {  
  if v = abort then  
    send abort() to P  
    t.abort()  
  else  
    send vote_request() to P  
  end  
end  
}
```

```
input vote(x) {  
  if x = abort then  
    send abort() to P  
    t.abort()  
  else  
    count++  
    if count = n then  
      send commit() to P  
      t.commit()  
    end  
  end  
end  
}
```

Participant: P = { P₁, ..., P_n }

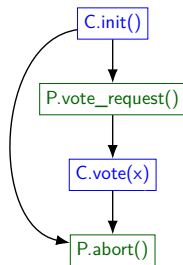
Variables

t // local part of transaction
v // own vote (commit/abort)

```
input vote_request() {  
  reply vote(v)  
}
```

```
input abort() {  
  t.abort()  
}
```

```
input commit() {  
  t.commit()  
}
```



Message flow in the two-phase commit protocol

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    end  
  end  
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Participant: P = { P₁, ..., P_n }

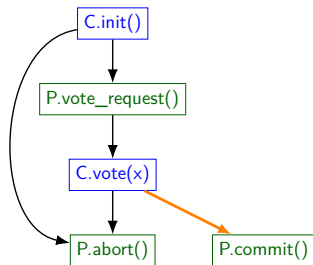
Variables

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v // own vote (commit/abort)

```
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  reply vote(v)  
}
```

```
input abort() {  
  t.abort()  
}
```

```
input commit() {  
  t.commit()  
}
```



Theorem

If an algorithm's message flow graph is acyclic, then the algorithm always terminates.

Basic assumptions

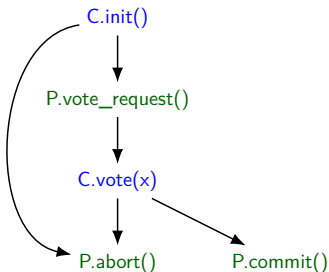
- All actions terminate
- No spontaneous actions
 - Each action consumes a message

Theorem

If an algorithm's message flow graph is acyclic, then the algorithm always terminates.

Advantages

- Practical language
- **Syntactic** criterion
 - **Static** analysis
 - Efficient: $\mathcal{O}(L + \#IAP^2)$
- **Visualization** as a tool



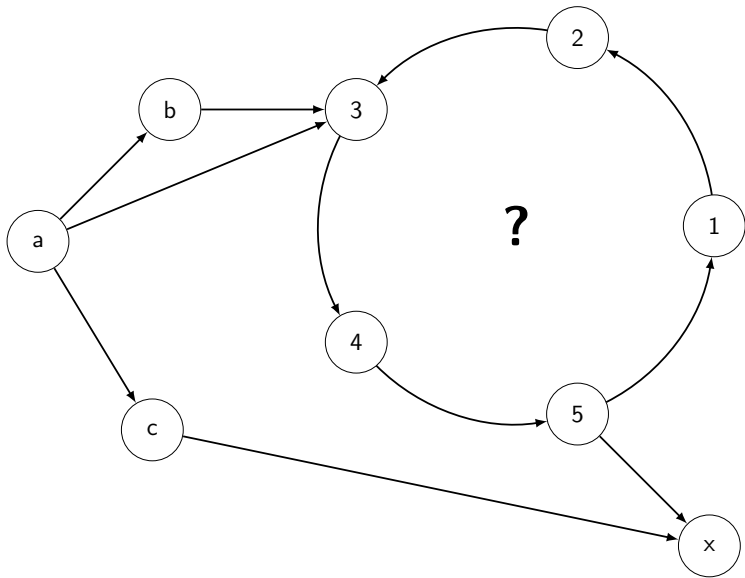
Theorem

If an algorithm's message flow graph is acyclic, then the algorithm always terminates.

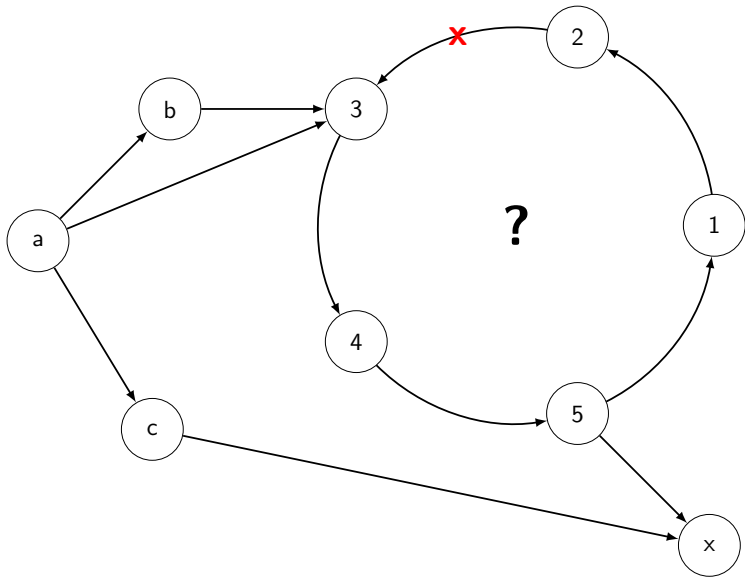
Disadvantages

- No spontaneous actions – timers?
- Precision?
 - Sequential protocols ✓
 - More complicated protocols?

Improving precision



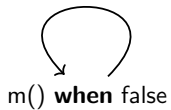
Non-traversable cycles



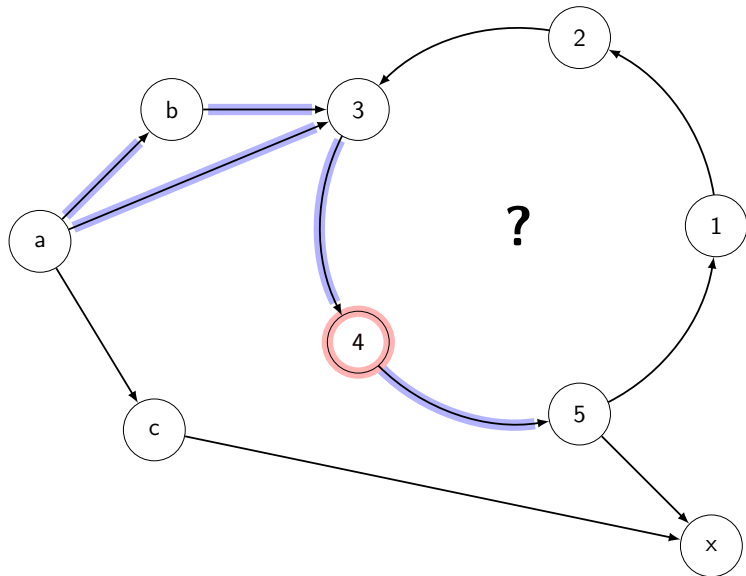
Non-traversable cycles: Impossible message flow

T

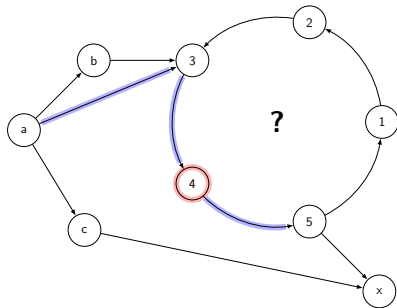
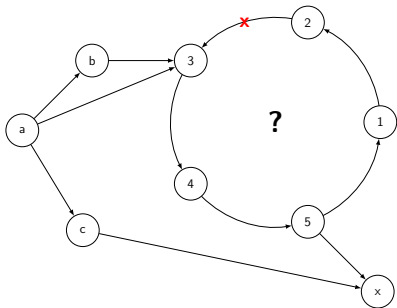
```
input m() when false {  
  send m() to T  
}
```



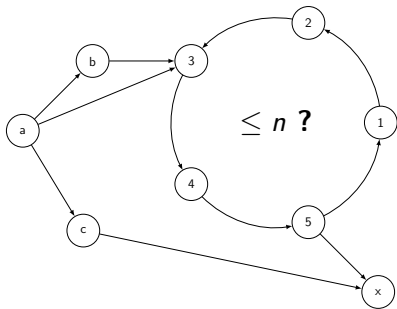
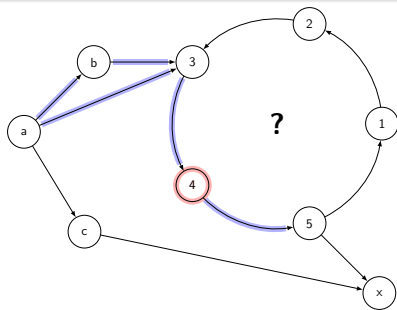
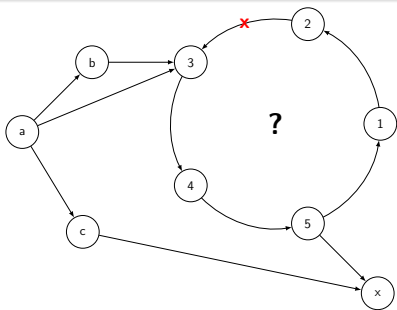
Non-traversable cycles (2)



Non-traversable cycles



Limited cycles



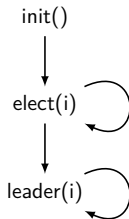
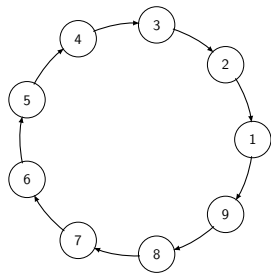
Leader election on a ring (Chang/Roberts 1979)

Ring node

Variables

leader // the current leader
self, next // own/next ID on ring

```
input init() {  
  send elect(self) to next  
}  
  
input elect(i) limit 2 {  
  if i = self then  
    send leader(i) to next  
  else  
    send elect(max(i, self)) to next  
  end  
end  
  
input leader(i) limit 1 {  
  leader := i  
  if i ≠ self then  
    send leader(i) to next  
  end  
end  
}
```



Chang and Roberts ring algorithm – unrolled

Ring node

Variables

leader, self, next

```
input init() {  
  send elect1(self) to next  
}
```

```
input elect1(i) {  
  if i = self then  
    send leader1(i) to next  
  else  
    send elect2(max(i, self)) to next  
  end  
end  
}
```

```
input elect2(i) {  
  if i = self then  
    send leader1(i) to next  
  else  
    send elect3(max(i, self)) to next  
  end  
end  
}
```

...

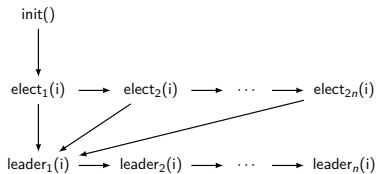
```
input elect2n(i) {  
  if i = self then  
    send leader1(i) to next  
  else  
    error "Limit exceeded"  
  end  
end  
}
```

```
input leader1(i) {  
  leader := i  
  if i ≠ self then  
    send leader2(i) to next  
  end  
end  
}
```

```
input leader2(i) {  
  leader := i  
  if i ≠ self then  
    send leader3(i) to next  
  end  
end  
}
```

...

```
input leadern(i) {  
  leader := i  
  if i ≠ self then  
    error "Limit exceeded"  
  end  
end  
}
```



- **Goal:** **Static termination analysis** for distributed algorithms
- **Approach:**
 - Event-driven model
 - Analyze possible **communication** between input-action pairs
 \rightsquigarrow **Message flow graph**
- **Result:** **Syntactic** termination criterion
 - **Acyclicity** implies termination
- Improving precision
- **Conclusion:** **Framework** for static termination analysis
- Implementation: <https://github.com/felixwiemuth/JIAL>